

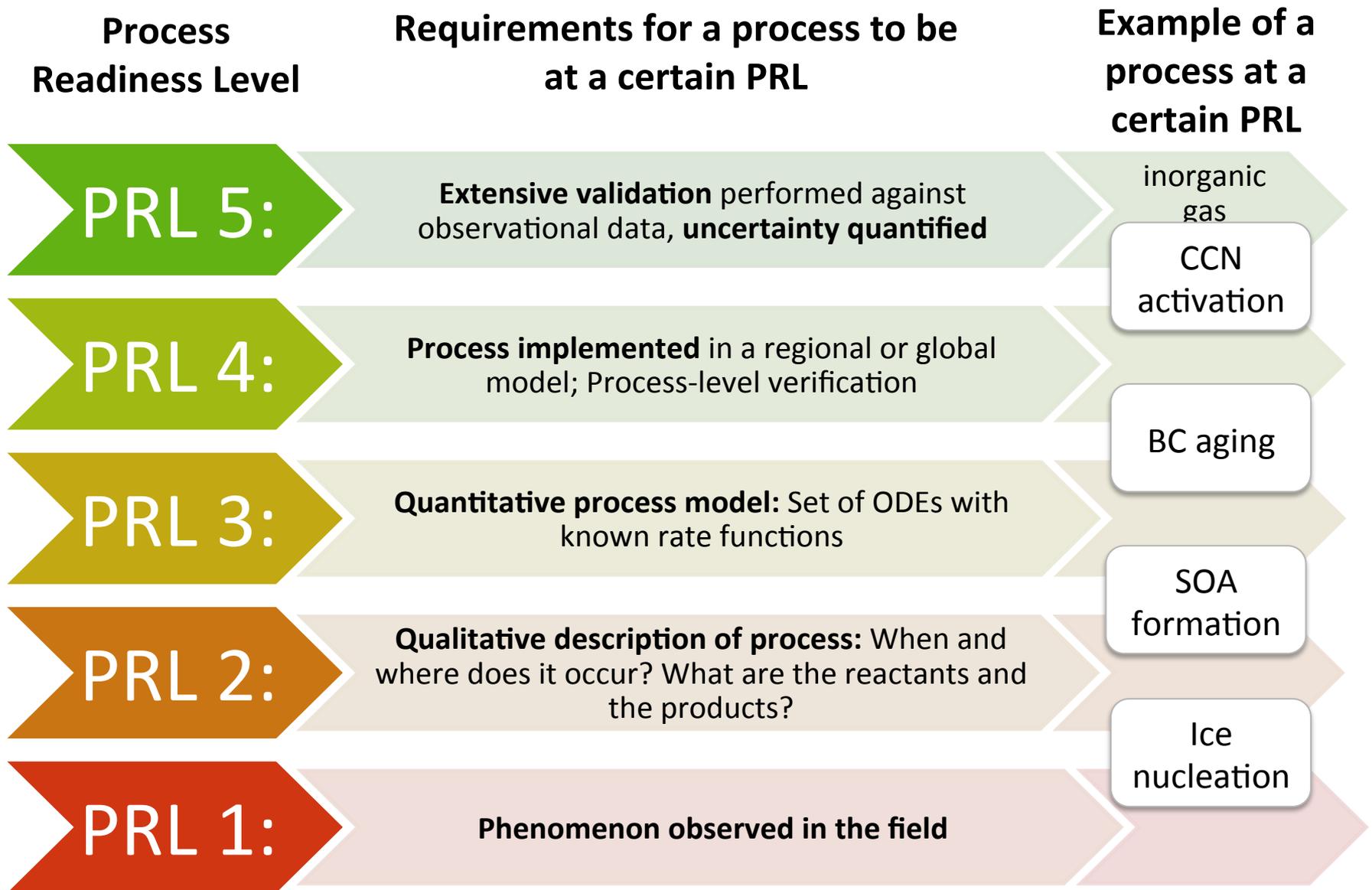
Challenges from the aerosol modeling community

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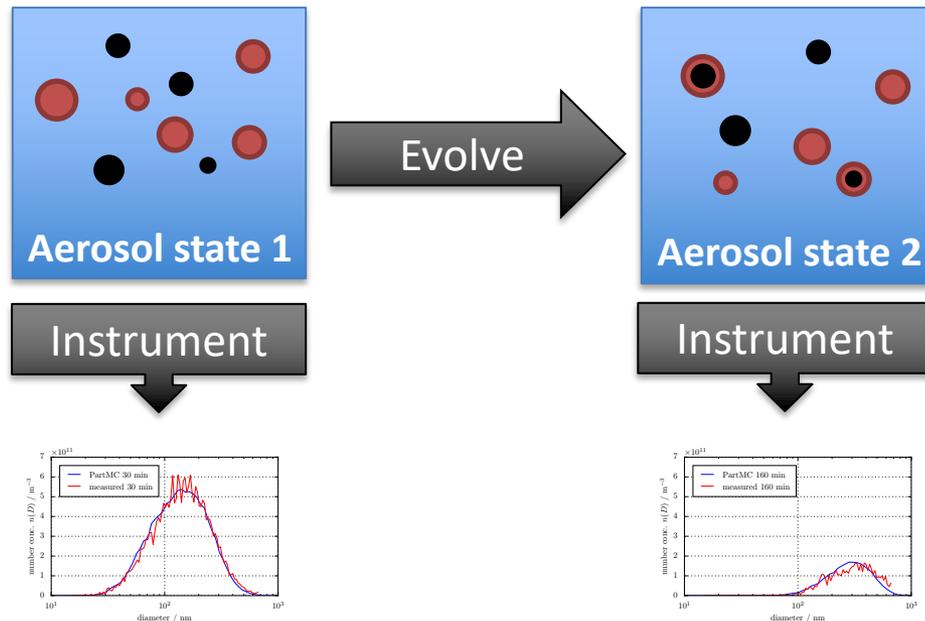
March 21, 2018

With apologies to Tim Onasch, Art Sedlacek, and Ernie Lewis



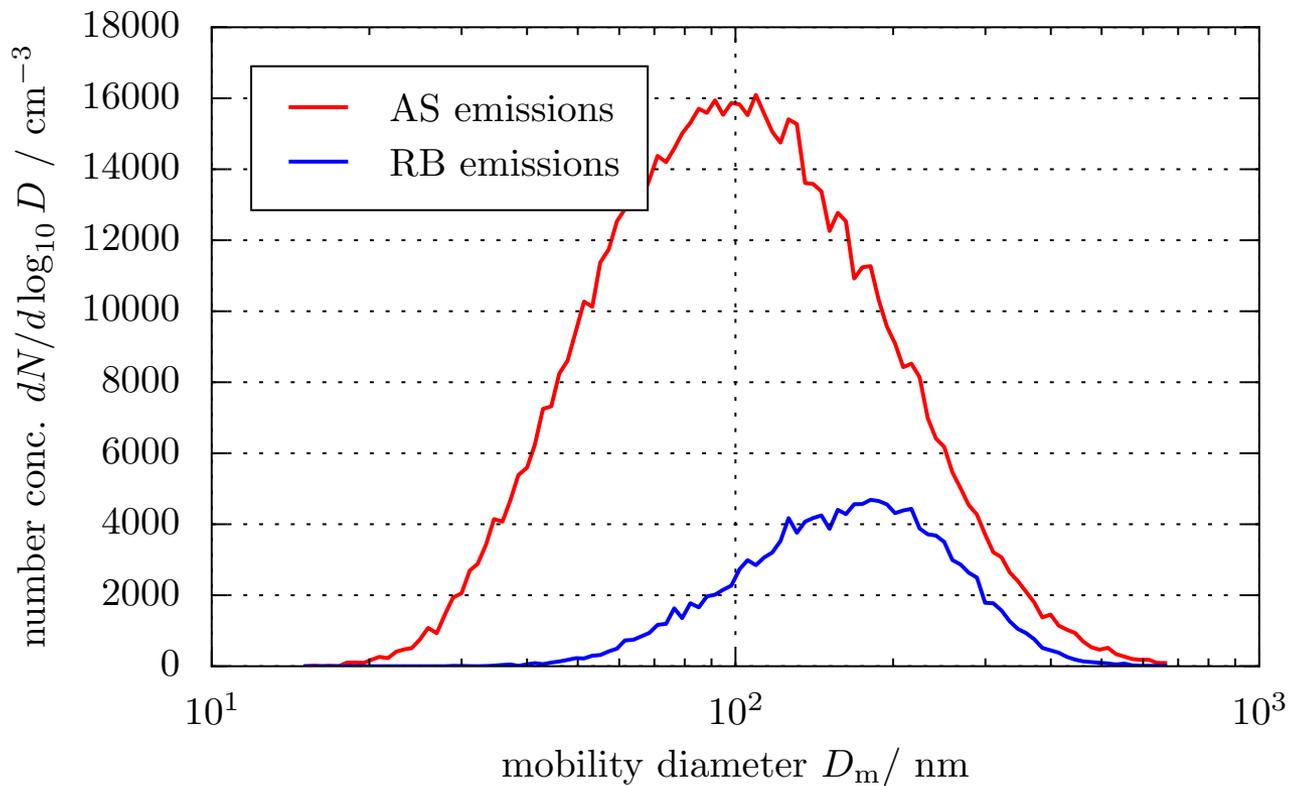
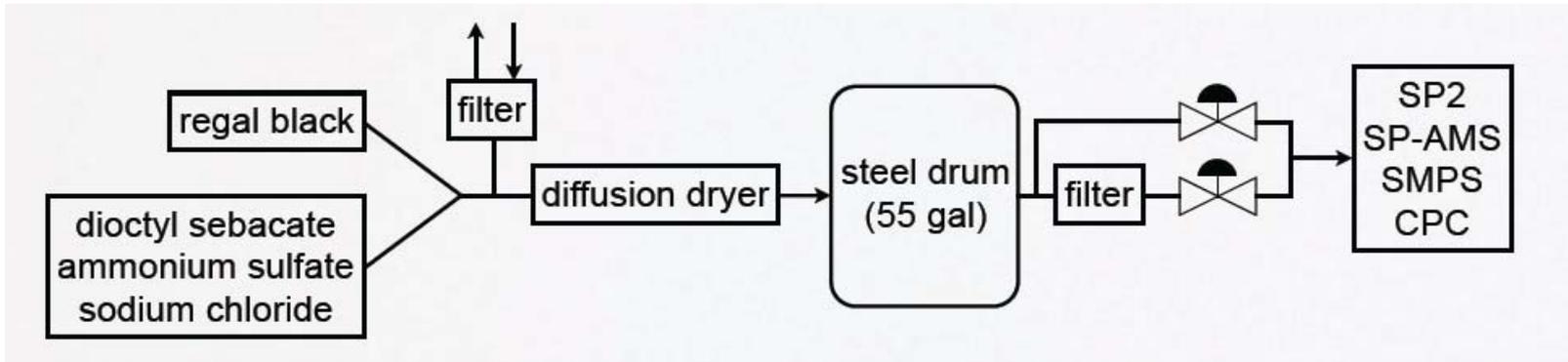
Model-measurement challenges

1. What is the aerosol **state**?
2. How does it **evolve**?
3. How is it **mapped** to measurements?

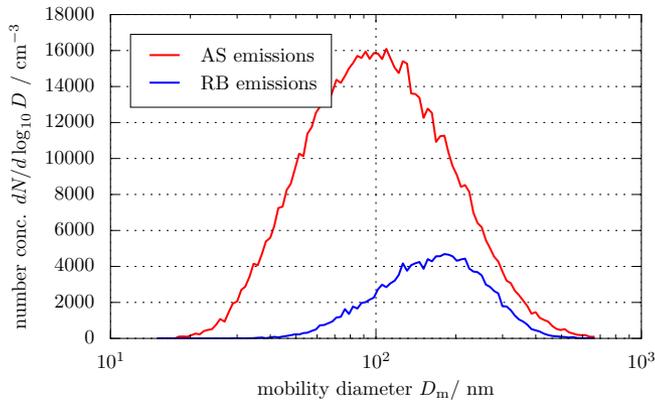


Aerosol standards

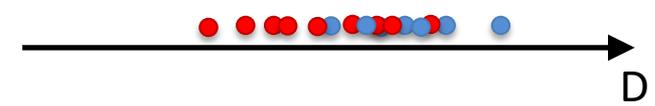
Dilution rate is about 2.6 L/min.



How does PartMC work?



Sample particle diameters



Particles are vectors:

- [3, 0]
- [7, 0]
- [0, 2]
- [0, 5]

AS

RB



Evolve

- [3, 0]
- [7, 2]
- [0, 5]

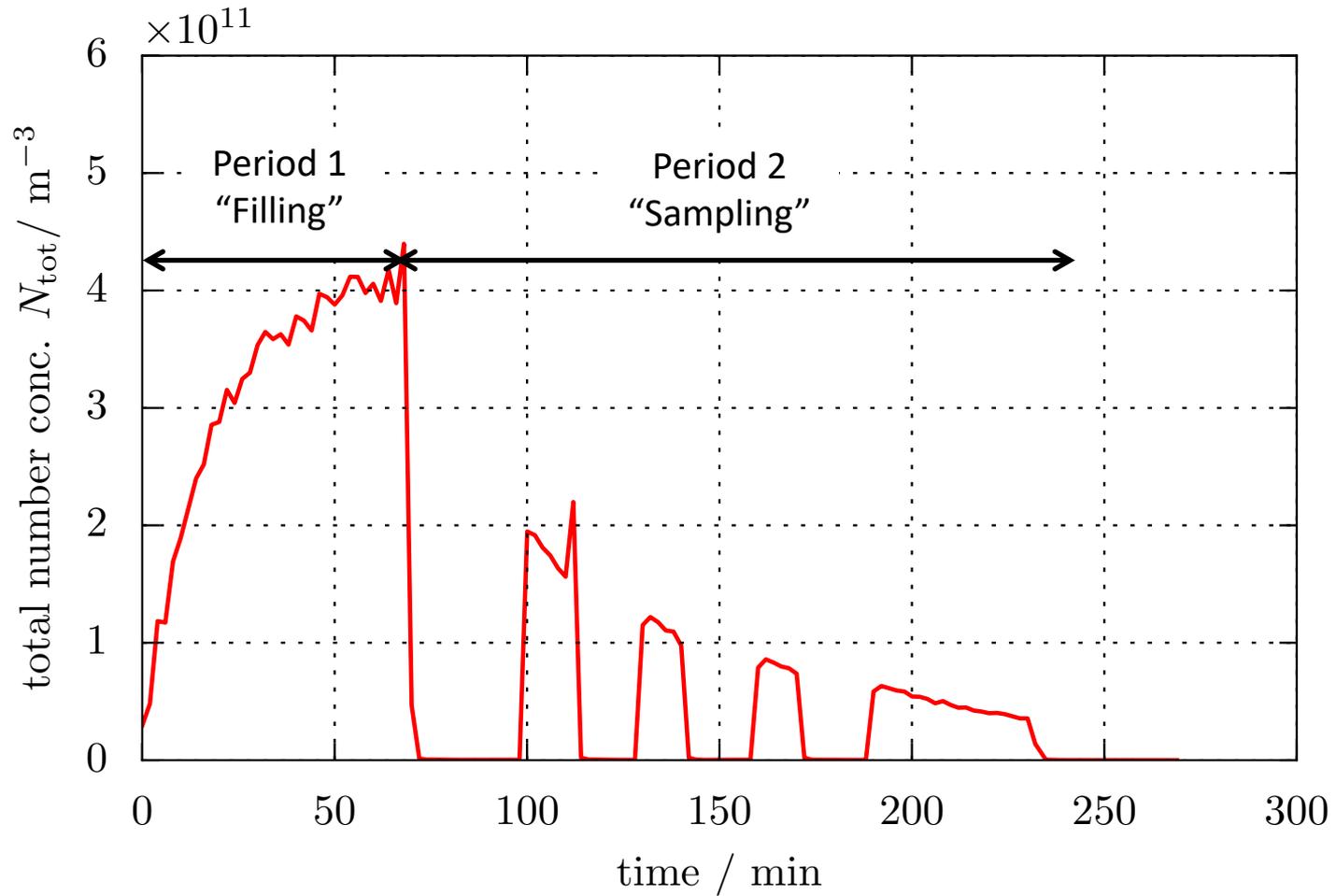
AS

RB

1. What is the aerosol **state**?

- Per-particle vectors
 - particle = $[m_{\text{BC}}, m_{\text{SO}_4}, m_{\text{H}_2\text{O}}, \dots, D_{\text{core}}, d_f, \dots]$
 - Mass of each species
 - But what is a “species”? Organics?
 - Also morphology (core diameter, inclusions, fractal dim, charge, ...)
- Even for non-particle-resolved models
 - Even when a model can't resolve some details, measurements of these are still important
 - Important for later re-modeling or re-processing

Time series of measured total number concentration on 8/28



All the specifications that are needed for the model

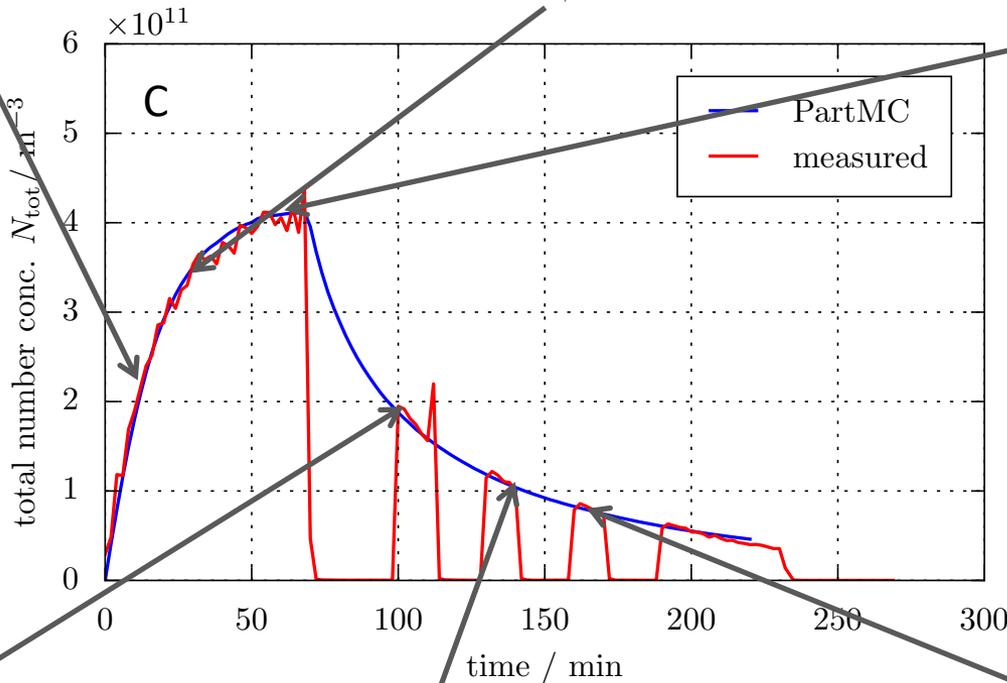
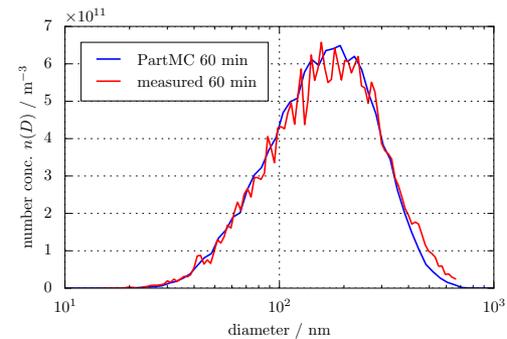
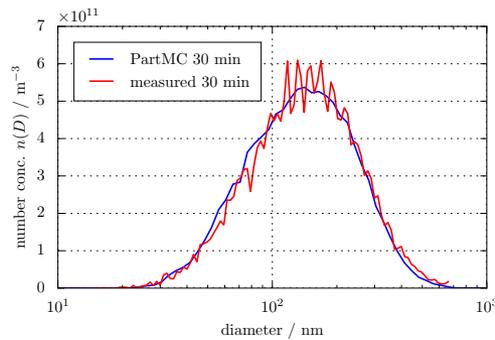
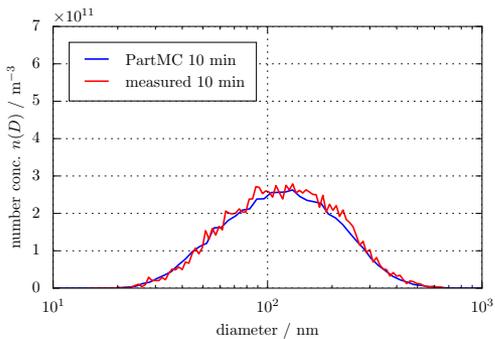
Quantity	Variable name	Value	Source
Barrel height	h_B	0.8954 m	Aerodyne
Barrel inner diameter	D_B	0.5715 m	Aerodyne
Barrel sedimentation area	A_S	0.2565 m ²	calculated
Barrel wall area	A_D	2.1206 m ²	calculated
Barrel volume	V_B	0.2297 m ³	calculated
Filling inflow for AS particles	R_{AS}	3 l min ⁻¹	Aerodyne
Filling inflow for RB particles	R_{RB}	3 l min ⁻¹	Aerodyne
Dilution outflow during Period 1	R_{dil1}	6 l min ⁻¹	$R_{AS} + R_{RB}$
Dilution outflow during Period 2	R_{dil2}	2.5 l min ⁻¹	Aerodyne
Relative humidity	RH	10%	Aerodyne
Temperature	T	293 K	Aerodyne
Pressure	p	10 ⁵ Pa	Aerodyne
Fractal dimension	d_f	2.3	Tian et al. [3]
Wall loss parameter	k_D	0.06 m	Tian et al. [3]
Wall loss parameter	a	0.25	Theoretical, Bunz and Dlugi [1], Fuchs [2]
Radius of primary particles	R_0	10 nm	assumed
Volume filling factor	f	1.43	Tian et al. [3]
Total number conc.	N_{tot}	dynamic	
Number conc. of AS particles	N_{AS}	11,075 cm ⁻³	Eq. (1)
Number conc. of RB particles	N_{RB}	2,312 cm ⁻³	Eq. (1)
Filling rate for AS particles	λ_{AS}	2.177 × 10 ⁻⁴ s ⁻¹	Eqn. (2)
Filling rate for RB particles	λ_{RB}	2.177 × 10 ⁻⁴ s ⁻¹	Eqn. (2)
Dilution rate during Period 1	λ_{dil1}	4.354 × 10 ⁻⁴ s ⁻¹	Eqn. (2)
Dilution rate during Period 2	λ_{dil2}	1.814 × 10 ⁻⁴ s ⁻¹	Eqn. (2)
Wall loss	L_{wall}	dynamic	Eqn. (4) in Tian et al. [3]
Coagulation loss	L_{coag}	dynamic	Eqn. (1) Tian et al. [3]

Fitted or
guessed

Uncertain

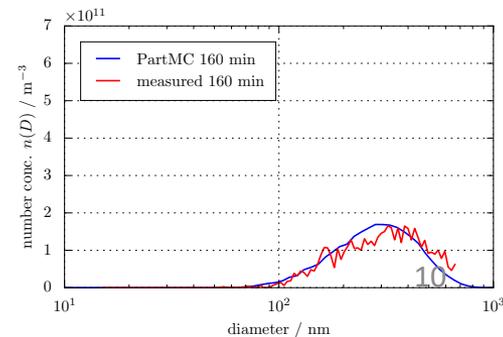
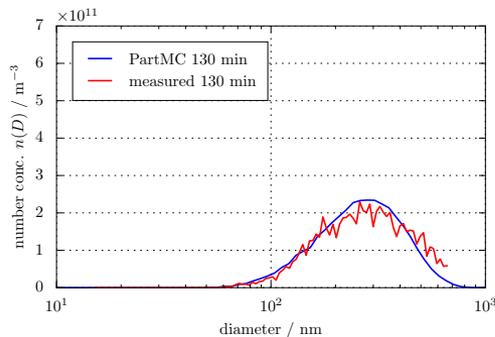
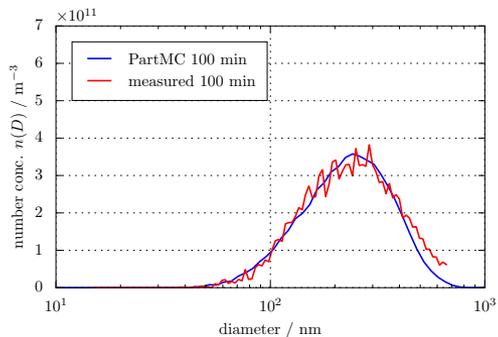
2. How does the state **evolve**?

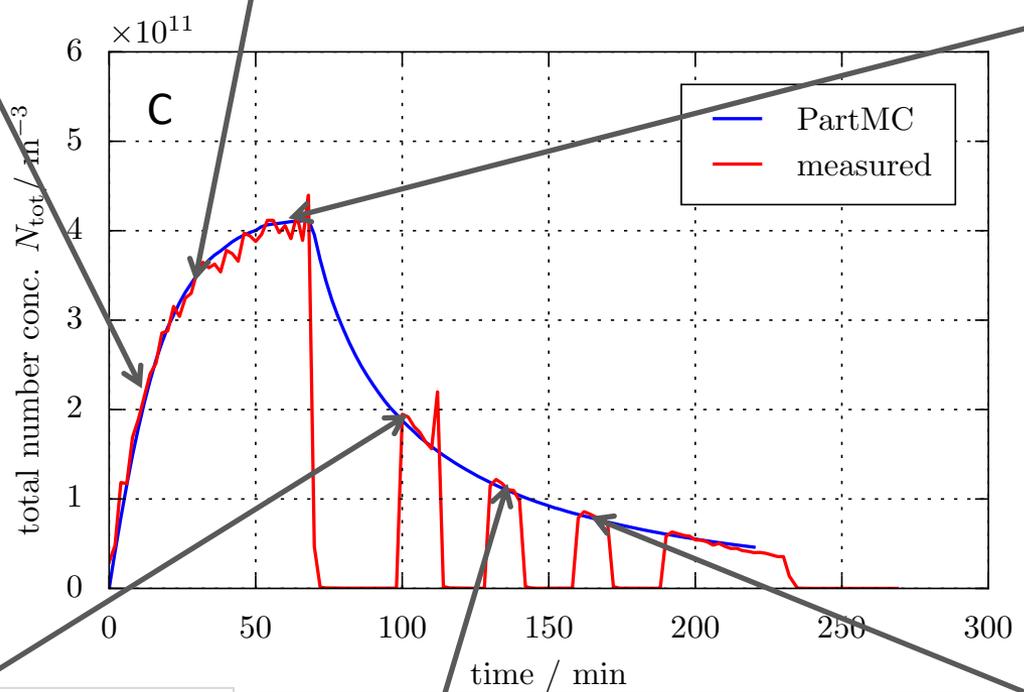
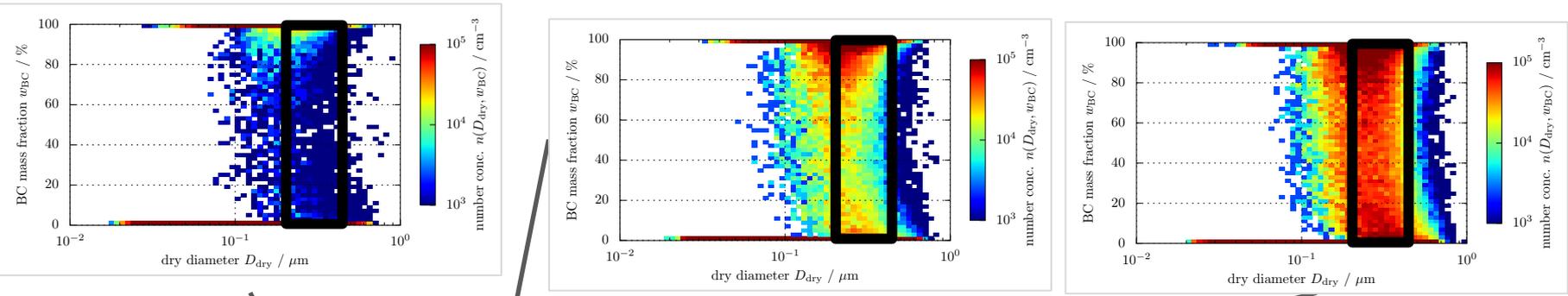
- Well-characterized inputs
 - Having to fit parameters is possible but painful
- All parameters along the way measured
 - Gas, environment, walls, fluxes
 - Unmeasured time-varying parameters are a nightmare (e.g., variable dilution rates)
- State measured periodically



Comparison of size distributions

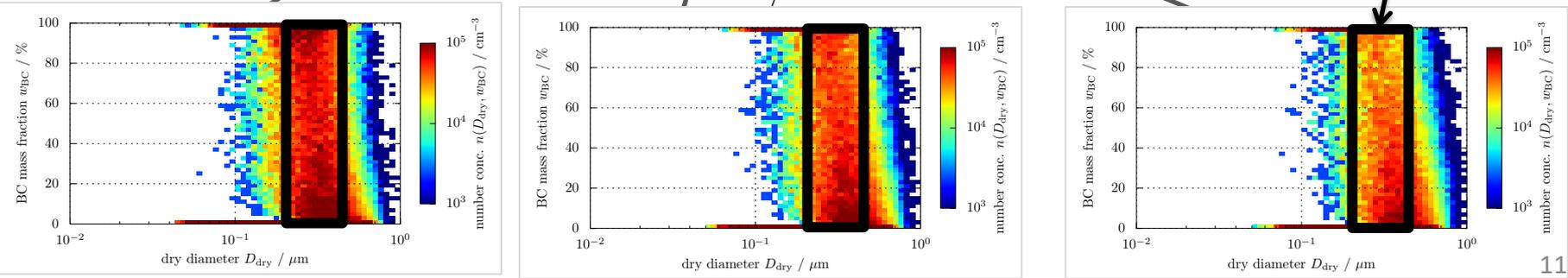
PartMC underpredicts the right side of the distribution somewhat, but overall this is not bad.





BC mixing state evolution

The box indicates the range that the SP2 sees in the scattering channel (200 – 450 nm)

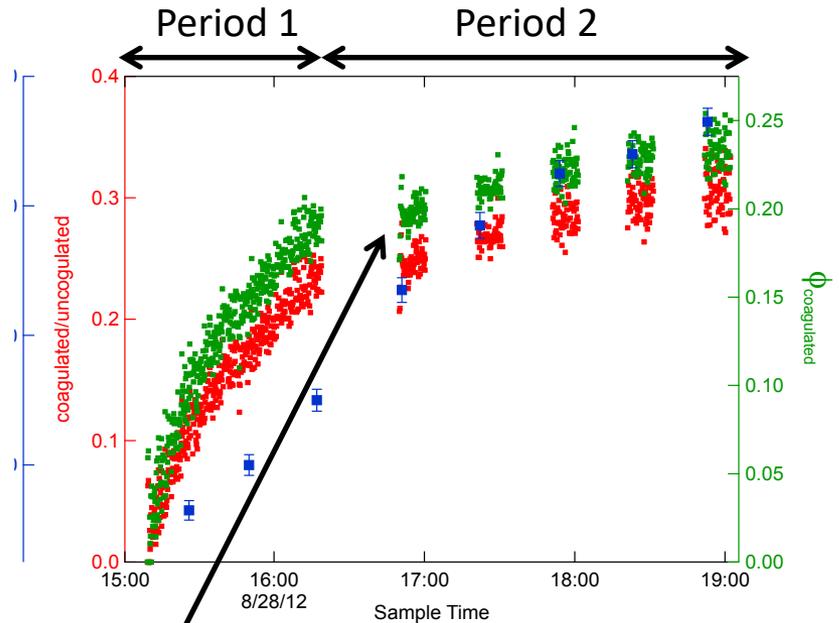
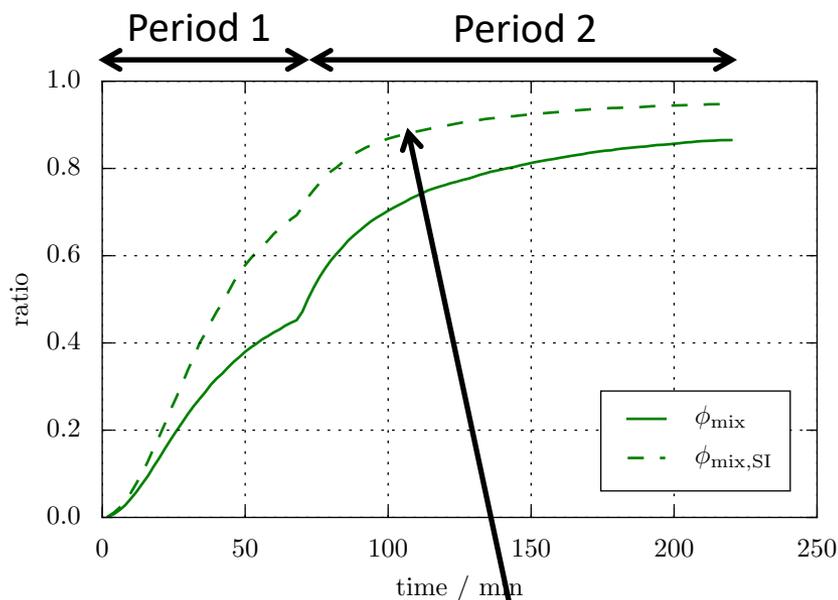


$$\phi_{\text{mix}} = \frac{N_{\text{mix}}}{N_{\text{BC}} + N_{\text{mix}}}$$

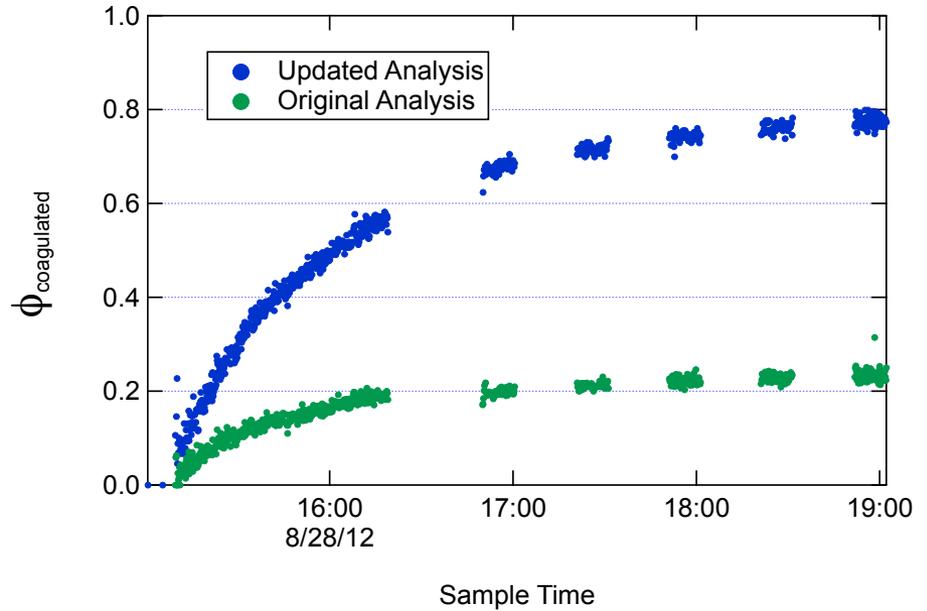
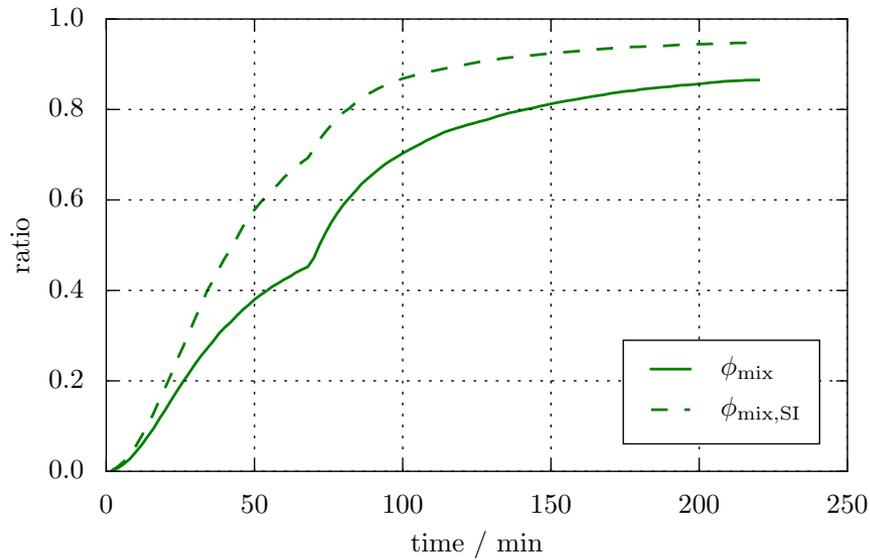
Fraction of mixed particles

$$\phi_{\text{mix,SI}} = \frac{N_{\text{mix,SI}}}{N_{\text{BC,SI}} + N_{\text{mix,SI}}}$$

Fraction of mixed particles in the size range
 $200 \text{ nm} < D_{\text{opt}} < 450 \text{ nm}$

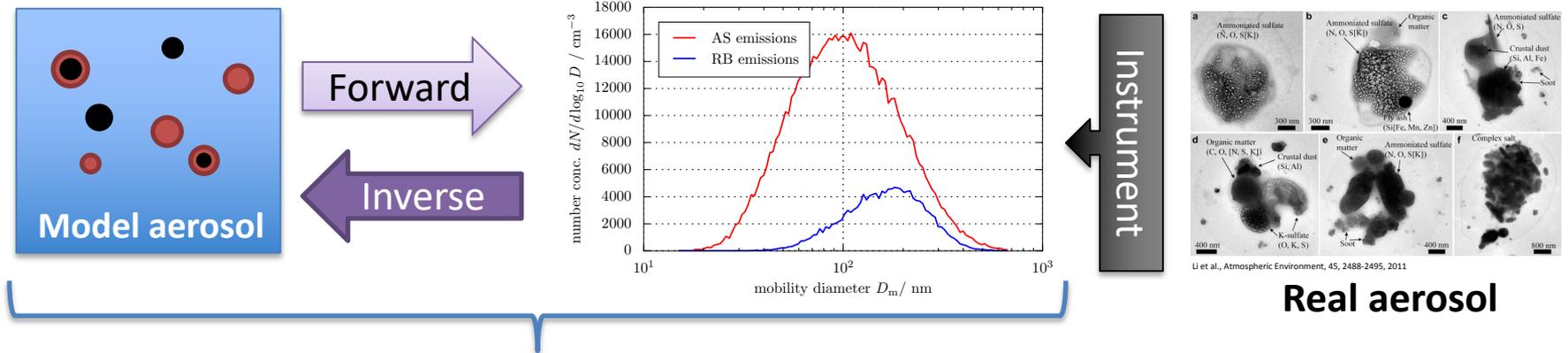


The green dashed line is supposed to be comparable with the green dots.



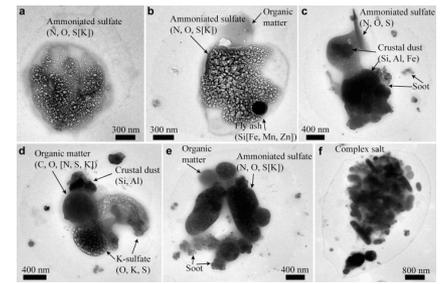
- Updated analysis: uncoagulated lag times $-0.4 \mu\text{s}$ to $+0.4 \mu\text{s}$
- Original analysis: uncoagulated lag times $-0.4 \mu\text{s}$ to $+1.6 \mu\text{s}$
- More data in the SP2 signal (bimodal scattering peaks) could better resolve this

3. How does aerosol state **map** to measurements?



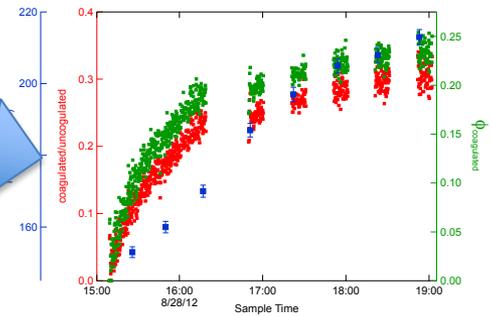
This is what we have to work with

- Inverse: measurement \Rightarrow state
 - Needed for initial condition
 - Key question: Can we recover a list of particle vectors from the measurements?
- Forward: state \Rightarrow measurement

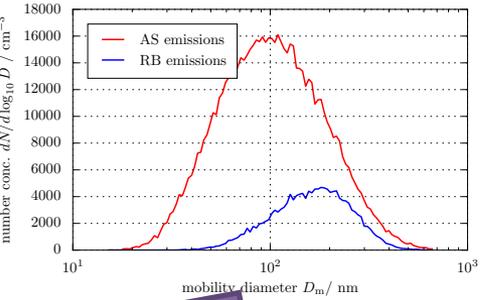
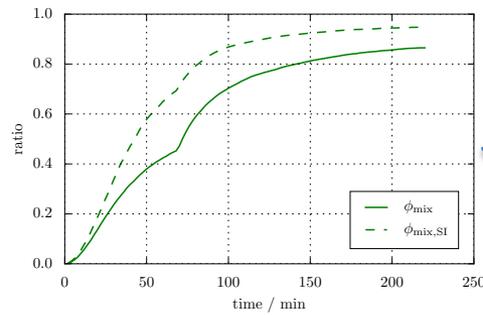


Li et al., Atmospheric Environment, 45, 2488-2495, 2011

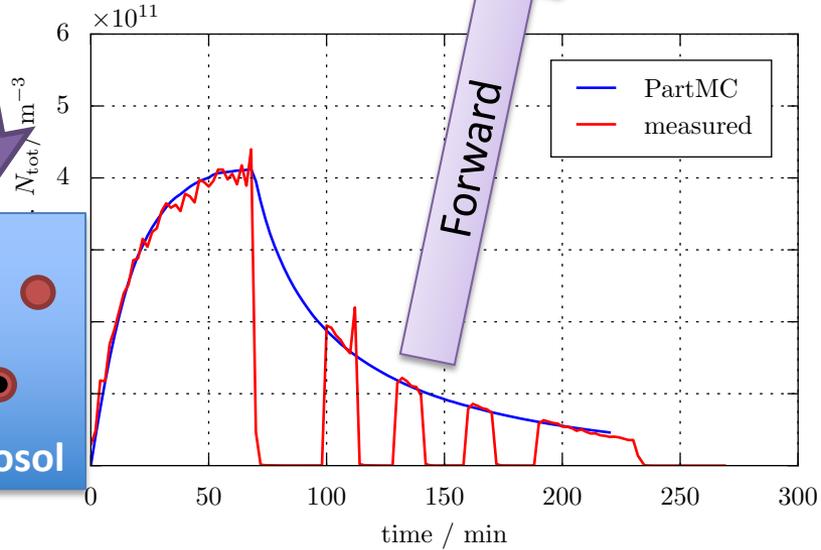
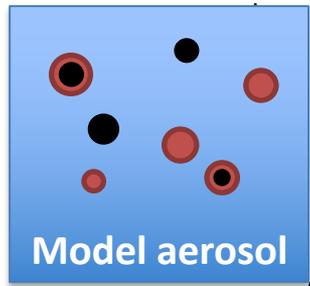
Instrument



Compare



Inverse



Forward

Why aerosol standards?

- Solve the **mapping** problems
 - Inverse: we measured y , what is really there?
 - Forward: we have x , what should we measure?
- Well understood mappings:
 - Mobility diameter \Leftrightarrow mass-equiv diameter
- Poorly understood mappings:
 - SP2 lag times
 - Single particle mass specs (“qualitative”)

Mapping to aerosol state

- How do we reconcile different instruments?
 - Important to get complete state
 - Given SP2, AMS, SPLAT in CARES — how do we initialize a model? What are the particles?
- We want full **state**: per-particle mass fractions
 - With error bars!

Mixing State FG: Connections

	Theory/ Metrics	PRM	SP2	Micro- scopy	SP mass spectro- metry	Bulk measure- ments	Remote sensing	RM/ GCM
Theory/ Metrics		high	medium	medium	low	low	low	low
PRM	high		medium	medium	medium	high	low	low
SP2	medium	medium		medium	medium	high	low	low
Micro- scopy	medium	medium	medium		medium	medium	low	low
SP mass spectro- metry	low	medium	medium	medium		medium	low	low
Bulk measure- ments	low	high	high	medium	medium		high	medium
Remote sensing	low	low	low	low	low	high		high
RM/ GCM	low	low	low	low	low	medium	high	